

Mimetic Preconditioners for Mixed Discretizations of the Diffusion Equation

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Class of problems

We consider the 2D steady-state linear diffusion

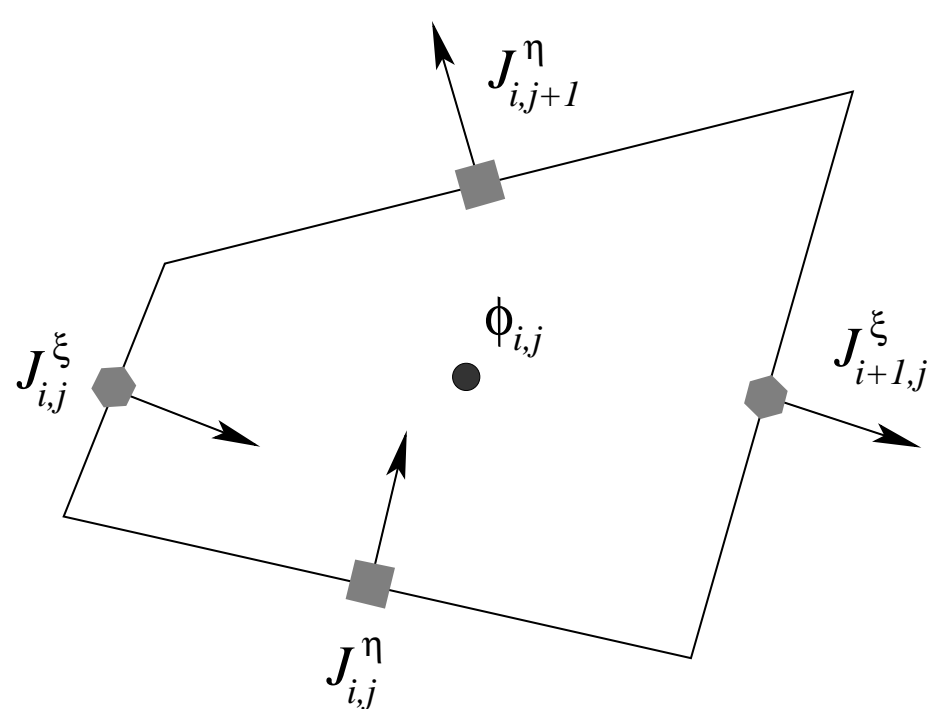
$$\begin{aligned}\nabla \cdot \mathbf{J} &= Q(x, y) \\ \mathbf{J} &= -D(x, y) \nabla \phi\end{aligned}$$

subject to the Dirichlet boundary condition $\phi(x, y) = g(x, y)$.

Key issues influencing the discretization and the linear solver include:

- $D(x, y)$ is defined on, and possibly discontinuous on, a very fine scale
- coarse-scale view of the fine-scale structure may be anisotropic
- although the grid is logically rectangular, it may be severely distorted.

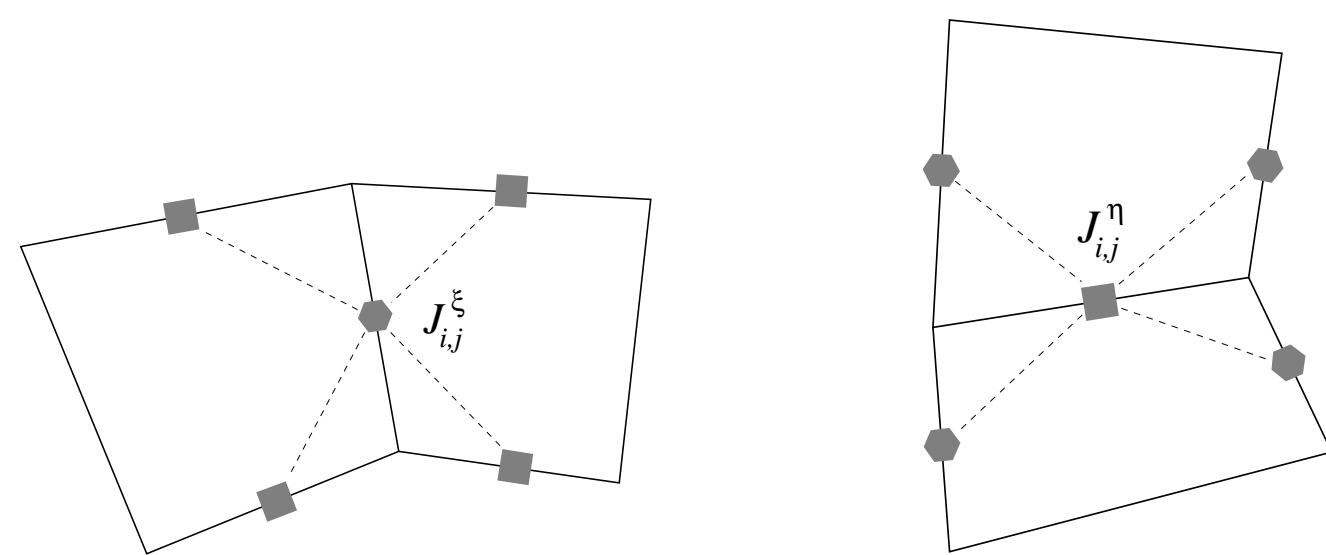
The Support Operator Discretization



$$\begin{aligned}(\text{current}) & \begin{bmatrix} \mathcal{A} & -\mathcal{D}^{\dagger} \mathcal{M} \\ -\mathcal{M} \mathcal{D} & 0 \end{bmatrix} \begin{bmatrix} \mathbf{J}_h \\ \phi_h \end{bmatrix} \\ (\text{balance}) & \end{aligned}$$

- Natural discretization of the divergence, \mathcal{D}
- Derive the corresponding gradient, $-\mathcal{D}^{\dagger} \mathcal{M}$
- Generate a symmetric, but indefinite, linear system.

The Schur Complement for ϕ_h



Stencil schematic for the sparsity structure of \mathcal{A} .

Properties of the Schur complement for ϕ_h :

- $\mathcal{S}_{\phi} = [\mathcal{M} \mathcal{D}] (\mathcal{A})^{-1} [\mathcal{D}^{\dagger} \mathcal{M}]$
- \mathcal{S}_{ϕ} is a symmetric positive definite matrix.
- \mathcal{S}_{ϕ} is a global matrix, but with sparse factors.
- ⇒ the matrix-vector product needed by CG is possible.

Mimetic Preconditioner I: A Simple Lumping of \mathcal{A}

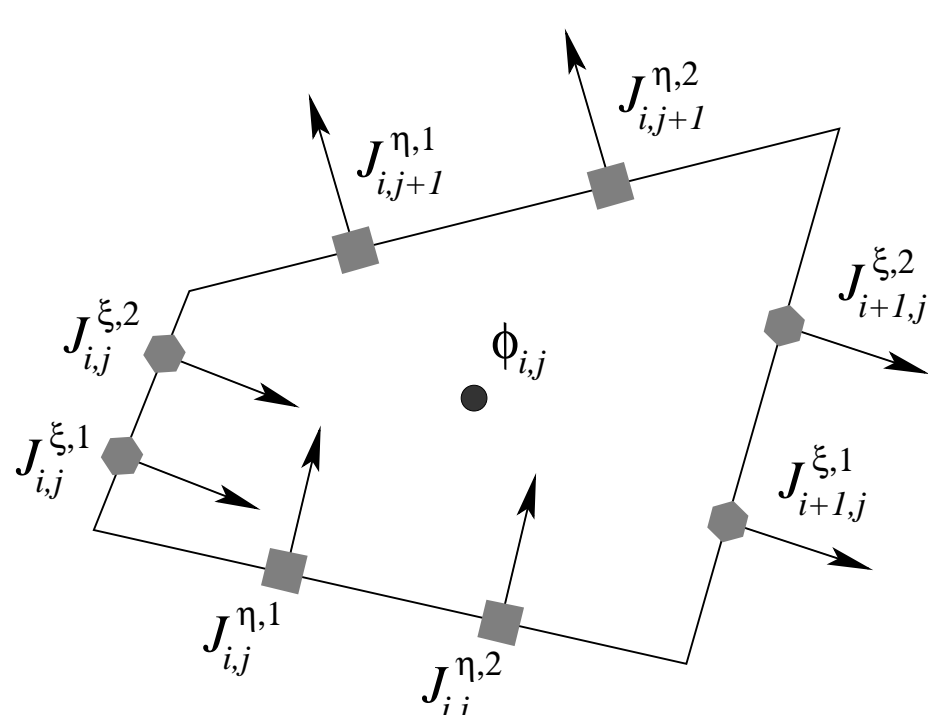
Diagonal approximation of the flux matrix:

$$\begin{bmatrix} \mathcal{A} & -\mathcal{D}^{\dagger} \mathcal{M} \\ -\mathcal{M} \mathcal{D} & 0 \end{bmatrix} \text{ lumping} \Rightarrow \begin{bmatrix} \widehat{\mathcal{A}} & -\mathcal{D}^{\dagger} \mathcal{M} \\ -\mathcal{M} \mathcal{D} & 0 \end{bmatrix}$$

Properties of the resulting Schur complement for ϕ_h :

- $\mathcal{S}_{\phi}^D = [\mathcal{M} \mathcal{D}] (\widehat{\mathcal{A}})^{-1} [\mathcal{D}^{\dagger} \mathcal{M}]$
- \mathcal{S}_{ϕ}^D is a symmetric positive definite matrix.
- \mathcal{S}_{ϕ}^D has a 5-point cell-based stencil
- Approximately invert \mathcal{S}_{ϕ}^D with a single V-cycle of multigrid.

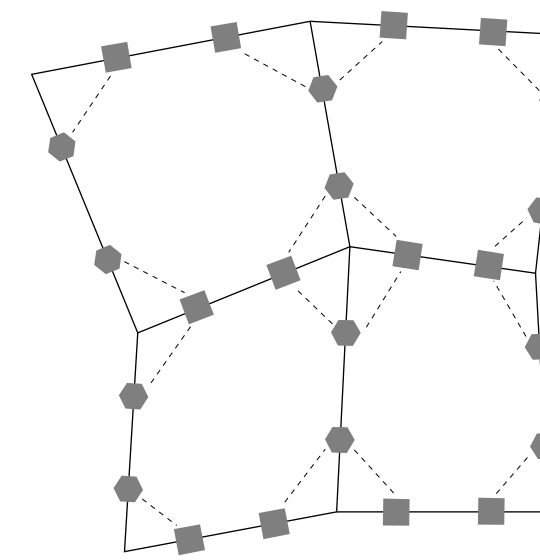
Mimetic Preconditioner II: Two-Flux Support Operator



$$\begin{aligned}(\text{current}) & \begin{bmatrix} \widetilde{\mathcal{A}} & -\widetilde{\mathcal{D}}^{\dagger} \mathcal{M} \\ -\mathcal{M} \widetilde{\mathcal{D}} & 0 \end{bmatrix} \begin{bmatrix} \widetilde{\mathbf{J}}_h \\ \phi_h \end{bmatrix} \\ (\text{balance}) & \end{aligned}$$

- Natural discretization of the divergence, $\widetilde{\mathcal{D}}$
- Derive the corresponding gradient, $-\widetilde{\mathcal{D}}^{\dagger} \mathcal{M}$
- Generate a symmetric, but indefinite, linear system.

The Schur Complement for ϕ_h



Schematic for the structure of $\widetilde{\mathcal{A}}$

⇒ Order $\widetilde{\mathbf{J}}_h$ around vertices, then $\widetilde{\mathcal{A}}$ has a block diagonal structure, with 4x4 blocks.

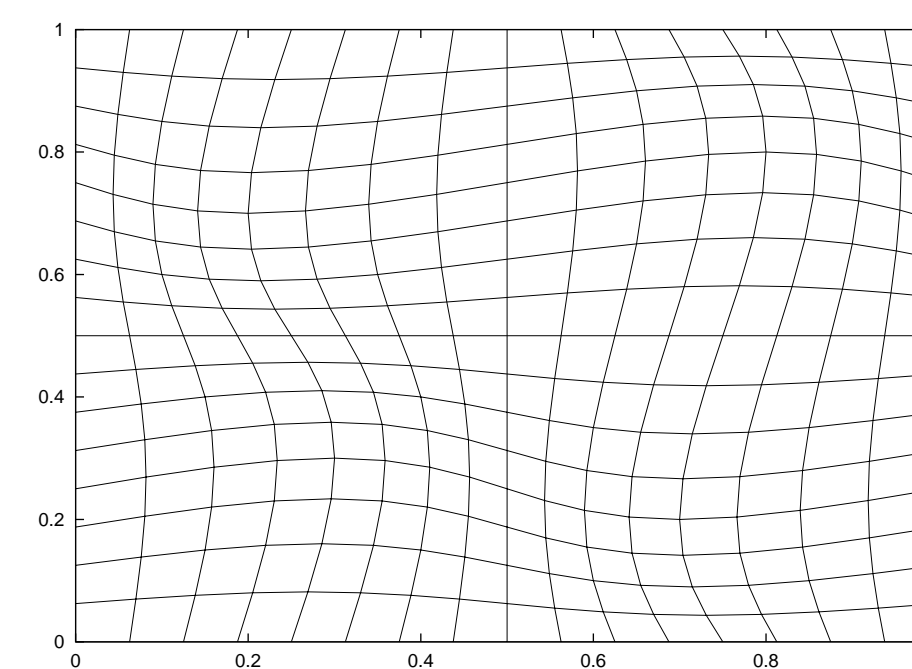
Properties of the resulting Schur complement for ϕ_h :

- $\mathcal{S}_{\phi}^{TF} = [\mathcal{M} \widetilde{\mathcal{D}}] (\widetilde{\mathcal{A}})^{-1} [\widetilde{\mathcal{D}}^{\dagger} \mathcal{M}]$
- \mathcal{S}_{ϕ}^{TF} is a symmetric positive definite matrix.
- \mathcal{S}_{ϕ}^{TF} has a 9-point cell-based stencil (second order on smooth grids)
- Approximately invert \mathcal{S}_{ϕ}^{TF} with a single V-cycle of multigrid.

Examples:

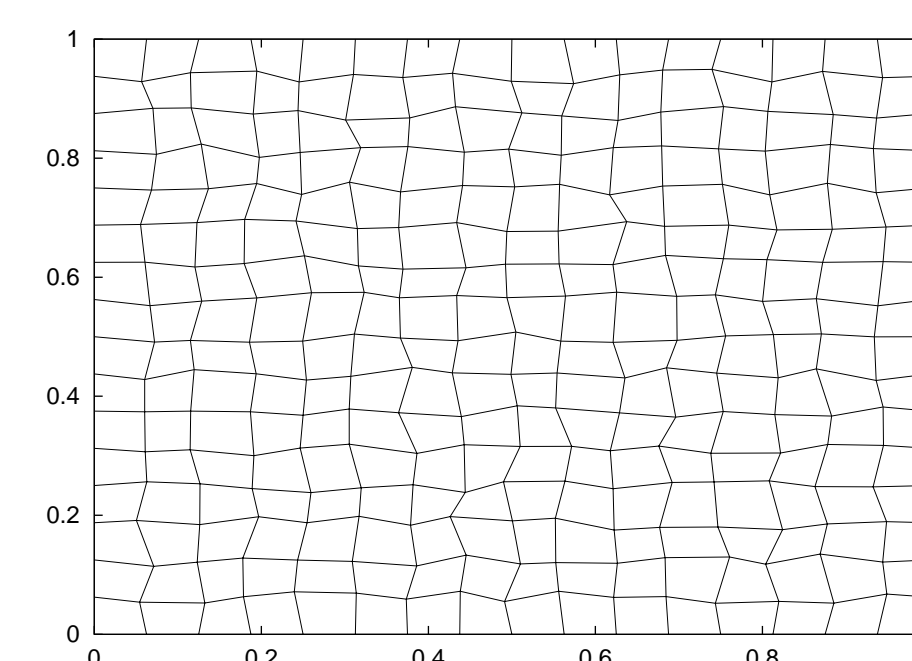
- $D(x, y) = 1$, Dirichlet boundary conditions, polynomial solution.
 - ⇒ the challenge arises from the distorted grid.
- Iteration counts are for CG on the cell-based system, \mathcal{S}_{ϕ}
 - ⇒ $CG(\mathcal{S}_{\phi})$ denotes only diagonal scaling of \mathcal{S}_{ϕ}
 - ⇒ $CG(\mathcal{S}_{\phi}^D)$ denotes the lumped preconditioner
 - ⇒ $CG(\mathcal{S}_{\phi}^{TF})$ denotes two-flux preconditioner
- Convergence criteria is a relative residual in the l_2 norm of 10^{-6} .
- A single V(1,1) cycle of BoxMG inverts the cell-based preconditioner.

A Smooth Grid (global smooth mapping)



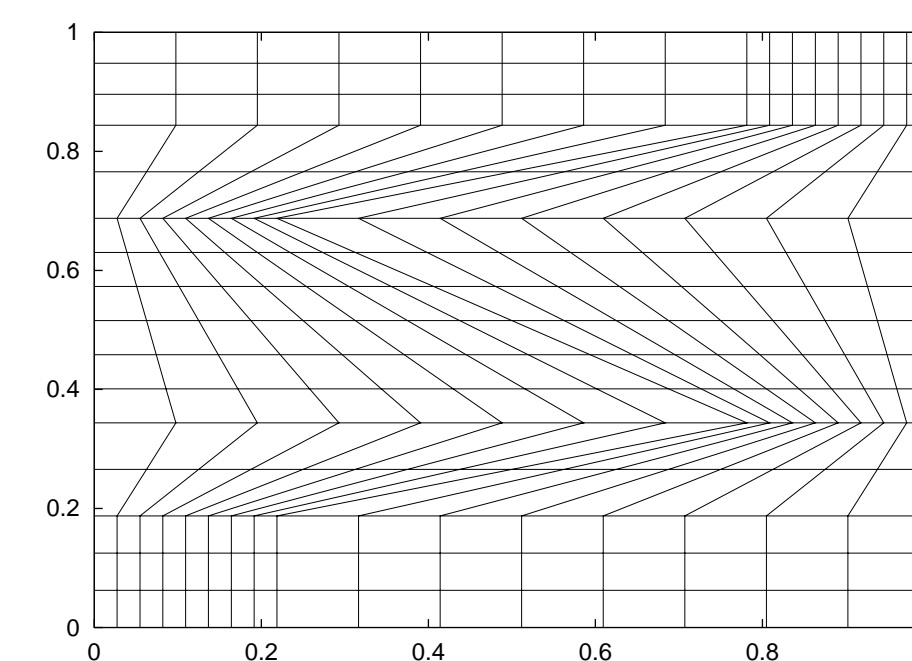
Mesh Size	Iteration Counts		
	$CG(\mathcal{S}_{\phi})$	$CG(\mathcal{S}_{\phi}^D)$	$CG(\mathcal{S}_{\phi}^{TF})$
16×16	43	9	4
32×32	85	10	5
64×64	164	10	5
128×128	319	10	5

A Randomly Perturbed Uniform Grid



Mesh Size	Iteration Counts		
	$CG(\mathcal{S}_{\phi})$	$CG(\mathcal{S}_{\phi}^D)$	$CG(\mathcal{S}_{\phi}^{TF})$
16×16	43	8	4
32×32	78	9	4
64×64	144	9	4
128×128	279	9	4

The Kershaw Grid



Mesh Size	Iteration Counts		
	$CG(\mathcal{S}_{\phi})$	$CG(\mathcal{S}_{\phi}^D)$	$CG(\mathcal{S}_{\phi}^{TF})$
16×16	53	34	15
32×32	108	44	15
64×64	211	52	14
128×128	406	58	13

Conclusions

PCG on the reduced scalar system

- augmented system leads to a 9-point cell-based preconditioner
 - ① robust with respect to grid distortion
 - ② convergence is h-independent
 - ③ readily extends to three dimensions
- inversion of \mathcal{A} needs to be done efficiently.

Avoiding the inversion of \mathcal{A}

- Preconditioned GMRES on the full system
- Preconditioned CG on the reduced scalar system of the *local* SOM.

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